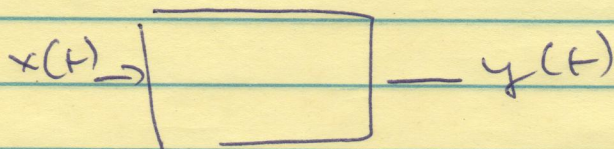


### Solution Homework 3

#### Pb 2.1



a)  $y(t) = 3x(t) + 1$  not linear because  
 $S(x_1 + x_2) = 3x_1(t) + 3x_2(t) + 1$   
 and  $S(x_1) + S(x_2) = 3x_1(t) + 1 + 3x_2(t) + 1$   
 $= 3x_1(t) + 3x_2(t) + 2$

b)  $y(t) = 3 \sin(t) x(t)$  is linear

c)  $\frac{dy}{dt} + t y(t) = x(t)$  is linear

d)  $\frac{dy}{dt} + 2y(t) = 3 \frac{dx}{dt}$  is linear

e)  $y(t) = \int_{-\infty}^t x(\tau) d\tau$  is linear

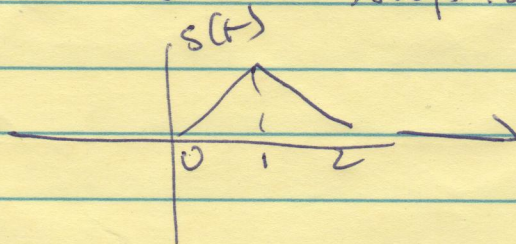
f)  $y(t) = \int_0^t x(\tau) d\tau$  is linear

g)  $y(t) = \int_{t-1}^{t+1} x(\tau) d\tau$  is linear

#### Pb 2.3

find the impulse response of an

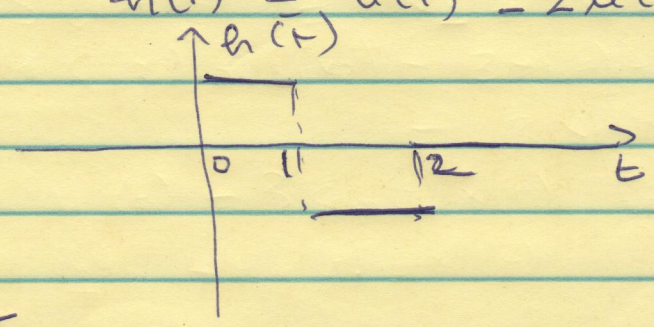
LTI system whose step response is



$h(t) = \frac{ds}{dt}$       the impulse response is the derivative of the step response

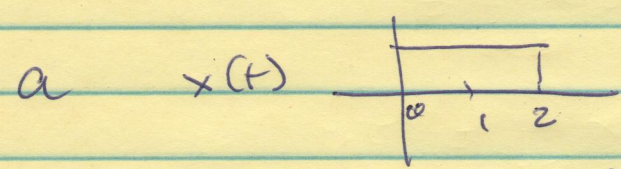
$$s(t) = r(t) - 2r(t-1) + r(t-2)$$

$$h(t) = u(t) - 2u(t-1) + u(t-2)$$

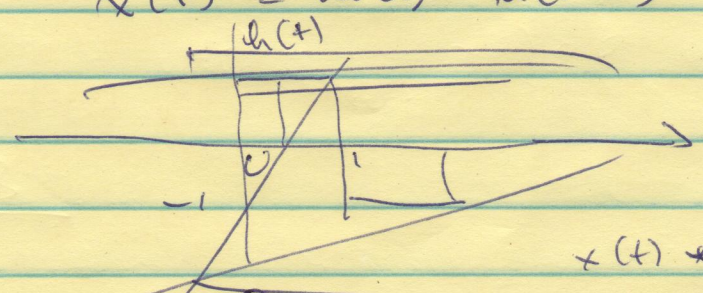


Ph 2.5

a)  $h(t)$  is the same as in probl. 2.3



$$x(t) = u(t) - u(t-2)$$

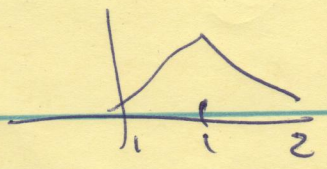


graphical convolution

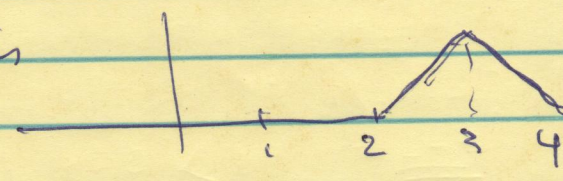
$0 < t < 1$

$$\int_0^t 1 dt = t$$

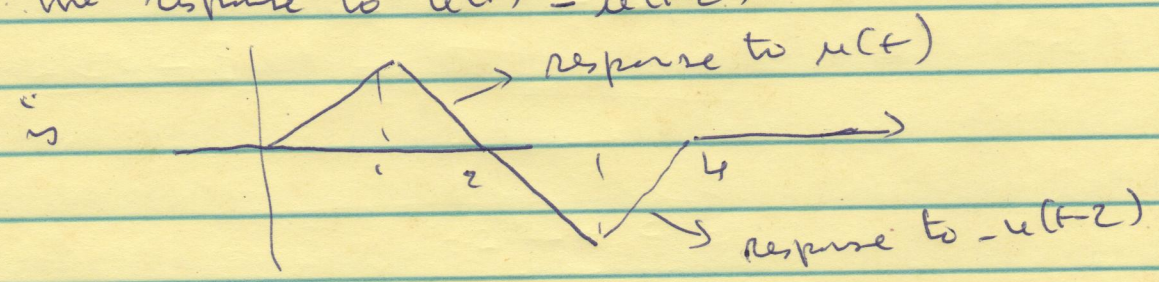
the response to  $u(t)$  is



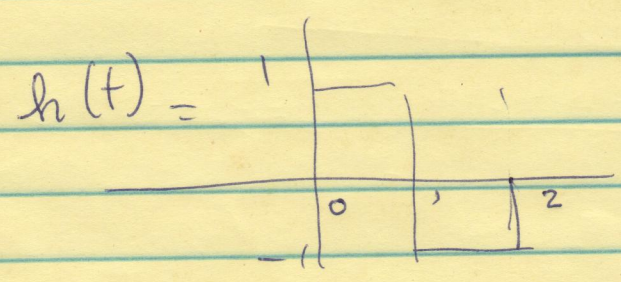
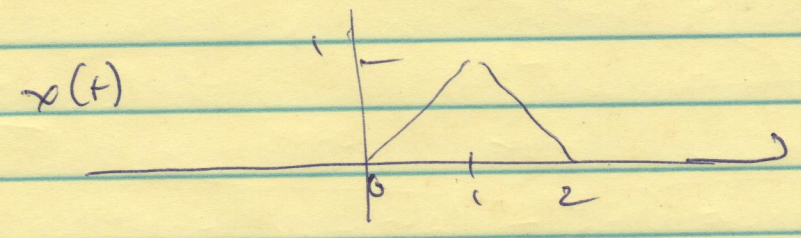
the response to  $u(t-2)$  is shifted by 2



So the response to  $u(t) - u(t-2)$



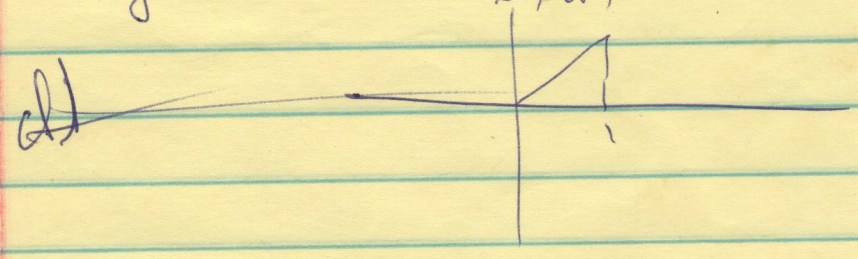
b)



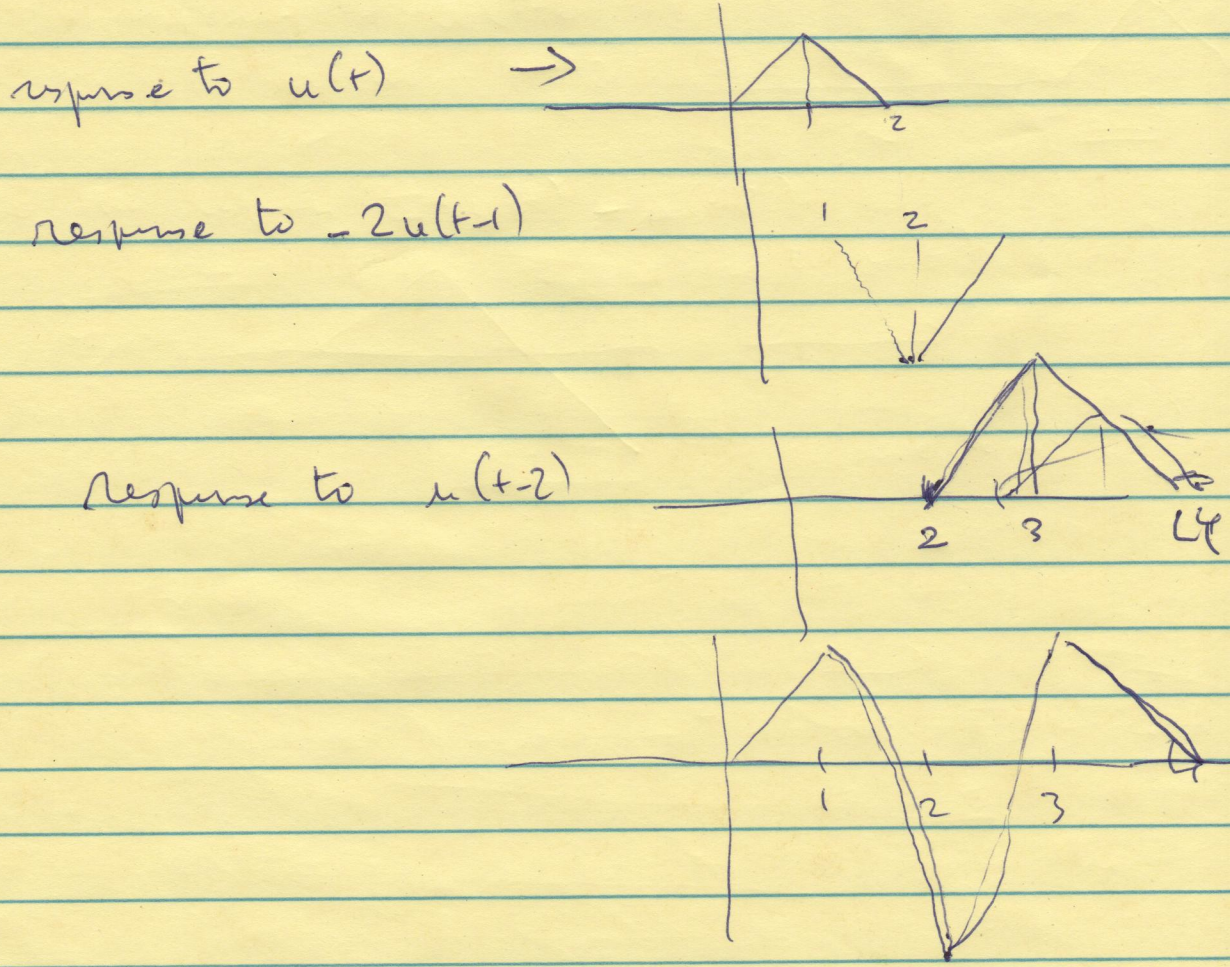
perform the graphical convolution

c)  $x(t) = h(t)$

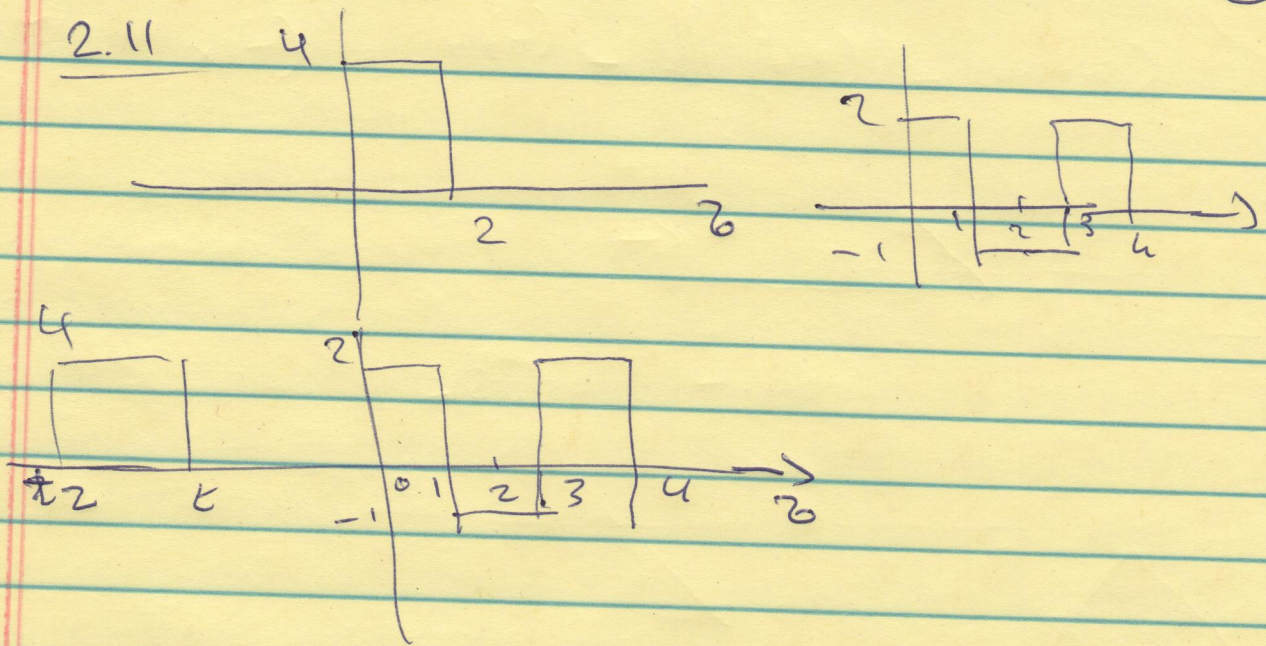
$y(t) = x(t) * h(t)$



c)  $x(t) = u(t) - 2u(t-1) + u(t-2)$



d) Graphical convolution



Graphical convolution

See the solution of practice test

2.12

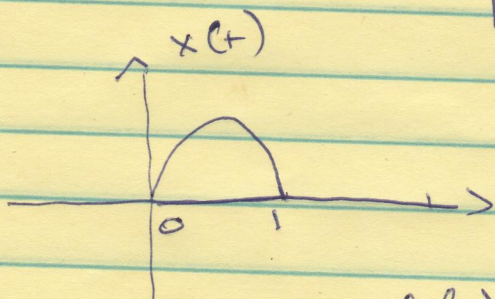
Same, do not do the analytical method

2.14

$$x(t) = \begin{cases} 0 & t < 0 \\ \sin \pi t & 0 \leq t \leq 1 \\ 0 & \text{elsewhere} \end{cases}$$

$$\omega_0 = \pi = \frac{2\pi}{T_0}$$

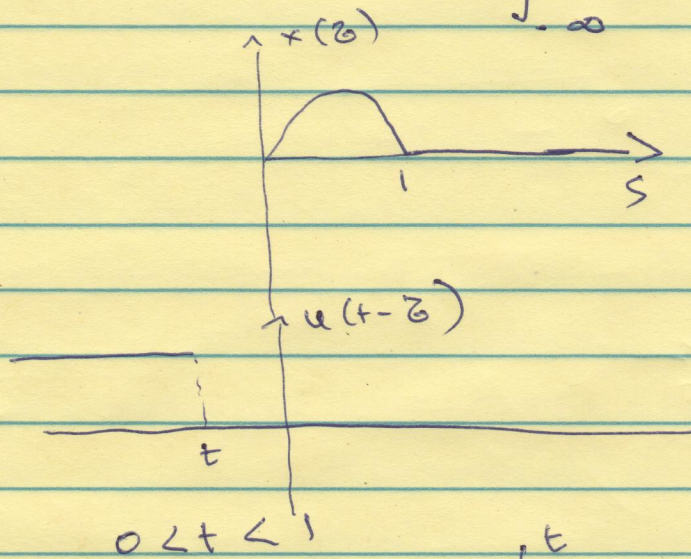
$$T_0 = 2s$$



$$h(t) = u(t)$$

(6)

$$x(t) * h(t) = \int_{-\infty}^{+\infty} x(\tau) h(t-\tau) d\tau$$



$$y(t) = \int_0^t \sin \pi \tau d\tau$$

$$= -\frac{1}{\pi} \left[ \cos \pi \tau \Big|_0^t \right]$$

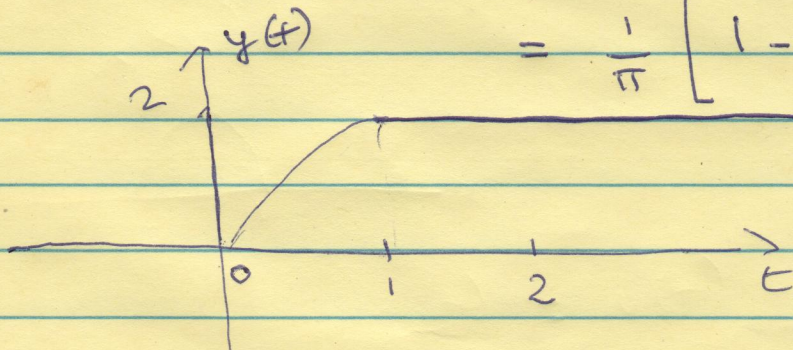
$$= -\frac{1}{\pi} [\cos \pi t - 1]$$

$$= \frac{1}{\pi} [1 - \cos \pi t]$$

$t \geq 1$

$$y(t) = \int_0^1 \sin \pi \tau d\tau$$

$$= \frac{1}{\pi} [1 - \cos \pi] = 2$$



2.15

$$a) u(t) * [\delta(t) - 3\delta(t-1) + 2\delta(t-2)]$$

$$= u(t) * \delta(t) - 3u(t) * \delta(t-1) + 2u(t) * \delta(t-2)$$

for any function  $f(t)$

$$f(t) * \delta(t - \tau_0) = f(t - \tau_0)$$

so

$$\rightarrow = u(t) - 3u(t-1) + 2u(t-2)$$

$$b) u(t) * [2u(t) - 2u(t-3)]$$

$$= 2u(t) * u(t) - 2u(t) * u(t-3)$$

$$u(t) * u(t) = r(t)$$

$$= 2r(t) - 2u(t) * u(t-3)$$

$$c) u(t) * [(t-1)u(t-1)]$$

$$u(t) * r(t-1)$$